Inverter/Vector Motors & Controls

## BALDOR · RELIANCE [].

VS1MD

**AC Micro Drive** 

**Applications:** Variable torque, constant torque or constant horsepower applications. New installations, replacments and orginal equipment manufatures (OEM).

**Features:** Volts per Hertz or Sensorless Vector Control with peak overload capacity of 200% and PID capability. Flexible mounting options with IP20 enclosure as standard and NEMA 1 kit option. Integral keypad, operator interface and local speed control. Programming by Groups makes it easy to navigate and find parameters. Basic Program Group contains the most common application related parameters. Power ratings up to 15 Hp in both 230V and 460V versions. Built-in braking transistor allows connection to remote braking resistor for enhanced performance needs.

Performance	Control Modes	V/Hz or Sensorless Vector	
Features	Operator Interface Module	Integral Drive Mounted	6
	Display Lines	4-Character LED Display	<sup>2</sup> O
	Programmable Preset Speeds	-Eight	- Mo
	Analog Outputs	0ne (0-10 VDC)	e l
	Auto Restart	Yes Up to 10 attempts	rat
	Frequency Avoidance	Three Bands	
	Fault History	Last Five Faults	
	Digital Inputs	Eight Completely Configurable Inputs	
	Digital Inputs Type	Fight compared by the second s	olt
Drive Specifications	Analog Inputs: Two Total	One: 0-10VDC or -10 to 10VDC One: 4-20mADC	75 <
Sinto opositionio	Digital Outputs: Two Total	One Onto-counied (Configurable) Form C Belay	57 57
	Meter Outputs	0-10 VDC: One Analog Lisaba Lisaba for Meter (Proportional to Frequency Output Current AC Output Voltage or DC Output Voltage)	∞ĕĕ
	Maximum Load	15 Ho @ 460 VAC	200
	Overload Capacity	To the Grow Web	••
		Divise Command: 0.01% of Max, Duthut Francesco, Anglor Command: 0.1% of Max, Output Francesco	
	Input Voltago Pangos	230 VAC (170 250: 460 VAC (222 52)	
	Reted Input Frequency	230 VAC (170-233), 400 VAC (323-326)	e
	Corrier Frequency	3U-00/IZ (±376)	ors
		1 - 13 KRZ (3 KRZ UBIDIU)	цĘ
	Operating temperature		° ≥
	Snubber (Dynamic Braking)	Built-in transistor	_
	Dynamic Braking External	Up to 150% Dynamic Braking with appropriately sized resistor	
	DC Injection Braking		
	Volts/Hz	Linear V/Hz, Quadratic V/Hz, Custom 4-Point V/Hz Curve	
	Sensorless Vector	Full Sensorless Vector Control with Autotune Function and motor model	νĽ
	Frequency Control Range	0-400 Hz	to te
	Accel/Decel	Eight independently adjustable sets of ramps	No H
	Time Range	0.1 to 600 Seconds	ю —
	S Curve Accel. & Decel.	Yes, with adjustable rounding percentage	
	Keypad Speed Control	Yes	
	Sink/Source Inputs	Selectable, 24 VDC Logic	s S
	Electronic Overload Trip	Electronic Motor Overload Inverse Time calculation with Programmable Warning Level	te e
	Communications	Built-in MODBUS-RTU (RS-485) Communications	Sor Vec
	PID Control	Built-in	er∕ & (
Protective Features	Under Voltage	Level Depends on Voltage Class (240, 480)	erte
	Ground Fault Protection	Ground Fault protection active during run	oto
	Output Short Circuit	Phase-to-Phase on Drive Output	Σ
	Over Temperature	Heatsink Monitor	
	DC Bus Overvoltage	DC Bus Level Trip	(0
	Drive Overload	Exceed Drive rating of 150% for One Minute	SI CI
	Over Current	Over-current/short-Circuit protection	oto
	Output Phase	Trips on open Output Phase	Σŭ
	Loss of Reference	Trips on Loss of Speed Command Signal	D
	Cooling Fan	Petects an inverter fan failure (renjace fan)	co
	Comm. Frror	Detects a communication error (fault)	
Agency Certifications			ú
Service Conditions	Altitude	1 000 m (3 300 ft ) derate by 1% per 100 m up to 2 000 m maximum	ke ke
	Amhient Temperature	IP20r -10°C (14°F) to 50°C (122°F)	Bra
	Storage Temperature	-20°C (-2°F) to 65°C (140°F)	tar ic E
	Relative Humidity	10% to 95% non-condensing	am
	Tholaavo Humbing		Sol



arm Duty Motors

Definite Purpose Motors

Unit Handling

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