

# Selection and ordering HT-direct motors 1FW4 water-cooled

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# Selection and ordering

## HT-direct motors 1FW4 water-cooled

### Overview



The motors are designed for the following rated voltages:

- 690 V $\sqrt{3}$ /50 Hz
- 400 V $\sqrt{3}$ /50 Hz
- 460 V $\sqrt{3}$ /60 Hz

Ambient temperature:  $-20\text{ }^{\circ}\text{C}$  to  $+40\text{ }^{\circ}\text{C}$ ; when operated below  $0\text{ }^{\circ}\text{C}$ , use anti-freeze in cooling water. Motors can optionally be ordered for higher ambient temperatures (see Page 2/6).

Cooling water inlet temperature: max.  $25\text{ }^{\circ}\text{C}$ ; at higher coolant inlet temperatures up to  $45\text{ }^{\circ}\text{C}$ , a motor Order No. must be selected in accordance with the derating factors (see Page 2/10). The order code for the higher cooling water inlet temperature (see Page 2/6) must also be specified in the order.

Degree of protection: IP55

Cooling method: IC71W

Type of construction: IM B3

Overview of torques and outputs  
in accordance with the rated speed

Rated speed rpm	Max. rated torque Nm	Max. rated output kW
200	42000	879
300	41000	1288
400	40000	1675
500	34235	1792
600	33000	2073
800	19000	1591

### Benefits

When high torques and low speeds are required for electrical drives in combination with compact dimensions and a low-noise design, the HT-direct motor with water-jacket cooling provides the ideal customer solution. Depending on the ambient conditions, water-jacket cooling generally provides maximum cooling performance – with minimal heating of the immediate environment.

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## Selection and ordering data

Rated torque Nm	Rated output <sup>1)</sup> kW	Frame size	Efficiency at 690 V		Rated current at			Norm. max. torque at 690 V <sup>2)</sup> $T_{max}/T_{rated}$	Moment of inertia J kgm <sup>2</sup>	Version with two galvanically isolated winding systems <sup>3)</sup>			Order No.	Weight, approx. kg	
			4/4-load %	4/4-load cos φ	690 V Y A	400 V Y A	460 V Y A			690 V Y	400 V Y	460 V Y			
<b>200 rpm, IP55 degree of protection, IMB3 type of construction</b>															
9375	196	401	94.4	0.89	205	335	305	1.5	19.4	-	-	-	1FW4401-1HA	0-1AA0	3040
11250	235	403	94.4	0.88	245	410	370	1.5	22.4	-	-	-	1FW4403-1HA	0-1AA0	3310
13125	274	405	94.7	0.89	280	485	425	1.5	26.1	-	-	-	1FW4405-1HA	0-1AA0	3650
15000	314	407	95.0	0.90	315	530	465	1.5	30.9	-	-	-	1FW4407-1HA	0-1AA0	4100
16215	339	451	93.1	0.79	400	740	650	1.5	37.9	-	-	-	1FW4451-1HA	0-1AA0	4010
18975	397	453	93.9	0.80	460	840	720	1.5	44.9	-	-	-	1FW4453-1HA	0-1AA0	4350
21850	457	455	94.3	0.81	550	900	830	1.5	51.5	-	-	-	1FW4455-1HA	0-1AA0	4680
27600	578	503	95.0	0.80	660	1190	990	1.5	89.3	-	-	-	1FW4503-1HA	0-1AA0	5610
32775	686	505	94.8	0.79	870	1350	1210	1.5	102.6	-	✓	-	1FW4505-1HA	0-1AA0	6110
37950	794	507	95.2	0.80	930	1720	1340	1.5	118.4	-	✓	✓	1FW4507-1HA	0-1AA0	6680
42000	879	508	95.6	0.82	930	1600	1400	1.5	139.3	-	✓	✓	1FW4508-1HA	0-1AA0	7440
<b>300 rpm, IP55 degree of protection, IMB3 type of construction</b>															
9060	284	401	95.7	0.90	275	475	420	1.5	19.4	-	-	-	1FW4401-1HB	0-1AA0	3040
10875	341	403	95.8	0.89	340	550	510	1.5	22.4	-	-	-	1FW4403-1HB	0-1AA0	3310
12690	398	405	96.1	0.89	390	640	580	1.5	26.1	-	-	-	1FW4405-1HB	0-1AA0	3650
14500	455	407	96.3	0.90	450	750	670	1.5	30.9	-	-	-	1FW4407-1HB	0-1AA0	4100
15860	498	451	95.3	0.79	560	1010	840	1.5	37.9	-	-	-	1FW4451-1HB	0-1AA0	4010
18560	583	453	95.6	0.81	700	1100	990	1.5	44.9	-	-	-	1FW4453-1HB	0-1AA0	4350
21375	671	455	95.8	0.81	890	1390	1220	1.5	51.5	-	✓	-	1FW4455-1HB	0-1AA0	4680
26700	838	503	96.2	0.81	960	1640	1440	1.5	89.3	-	✓	✓	1FW4503-1HB	0-1AA0	5610
31705	996	505	96.3	0.80	1170	1960	1680	1.5	102.6	-	✓	✓	1FW4505-1HB	0-1AA0	6110
36710	1153	507	96.5	0.80	1290	2330	1940	1.5	118.4	✓	✓	✓	1FW4507-1HB	0-1AA0	6680
41000	1288	508	96.7	0.82	1360	2220	2190	1.5	139.3	✓	✓	✓	1FW4508-1HB	0-1AA0	7440
<b>400 rpm, IP55 degree of protection, IMB3 type of construction</b>															
8750	366	401	96.4	0.90	360	580	530	1.5	19.4	-	-	-	1FW4401-1HC	0-1AA0	3040
10500	439	403	96.5	0.90	435	700	630	1.5	22.4	-	-	-	1FW4403-1HC	0-1AA0	3310
12250	513	405	96.7	0.91	485	850	750	1.5	26.1	-	-	-	1FW4405-1HC	0-1AA0	3650
14000	586	407	96.9	0.93	540	930	810	1.5	30.9	-	-	-	1FW4407-1HC	0-1AA0	4100
15510	649	451	96.0	0.80	710	1240	1100	1.5	37.9	-	✓	-	1FW4451-1HC	0-1AA0	4010
18150	760	453	96.4	0.82	800	1380	1210	1.5	44.9	-	✓	-	1FW4453-1HC	0-1AA0	4350
20900	875	455	96.5	0.81	950	1590	1370	1.5	51.5	-	✓	✓	1FW4455-1HC	0-1AA0	4680
25800	1080	503	96.8	0.83	1110	1880	1620	1.5	89.3	-	✓	✓	1FW4503-1HC	0-1AA0	5610
30635	1283	505	96.8	0.81	1420	2290	2270	1.5	102.6	✓	✓	✓	1FW4505-1HC	0-1AA0	6110
35475	1485	507	97.0	0.81	1610	4)	2270	1.5	118.4	✓	4)	✓	1FW4507-1HC	0-1AA0	6680
40000	1675	508	97.2	0.83	1780	4)	4)	1.5	139.3	✓	4)	4)	1FW4508-1HC	0-1AA0	7440
<b>Rated voltage</b>															
• 460 V Y															
• 690 V Y															
• 400 V Y															
Special voltage															
4 7 8 9															
Other rated speed with additional plain text															
-Z															

1) Temperature class 155 (temperature class F), used according to temperature class 155 (temperature class F)  
 2) Maximum torque  $T_{max}$  = Overload torque for 120 s (higher overload torques on request)

3) In the version with two galvanically isolated winding systems, two main terminal boxes 1XB1 631 are required.  
 - Not applicable  
 ✓ Applicable  
 4) Cannot be implemented

# Selection and ordering

## HT-direct motors 1FW4 water-cooled

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Rated torque Nm	Rated output <sup>1)</sup> kW	Frame size	Efficiency at 690 V		Rated current at			Norm. max. torque at 690 V <sup>2)</sup> $T_{max}/T_{rated}$	Moment of inertia J kgm <sup>2</sup>	Version with two galvanically isolated winding systems <sup>3)</sup>			Order No.	Weight, approx. kg
			4/4-load %	4/4-load cos φ	690 V √	400 V √	460 V √			690 V √	400 V √	460 V √		
<b>500 rpm, IP55 degree of protection, IMB3 type of construction</b>														
8440	441	401	96.8	0.91	415	680	610	1.5	19.4	-	-	-	1FW4401-1HD ■ 0-1AA0	3040
10125	530	403	96.9	0.90	510	840	740	1.5	22.4	-	-	-	1FW4403-1HD ■ 0-1AA0	3310
11810	618	405	97.0	0.90	590	960	830	1.5	26.1	-	-	-	1FW4405-1HD ■ 0-1AA0	3650
13500	706	407	97.2	0.95	630	1080	930	1.5	30.9	-	-	-	1FW4407-1HD ■ 0-1AA0	4100
15160	793	451	96.6	0.80	880	1400	1390	1.5	37.9	-	✓	✓	1FW4451-1HD ■ 0-1AA0	4010
17740	928	453	96.8	0.81	1050	1600	1580	1.5	44.9	-	✓	✓	1FW4453-1HD ■ 0-1AA0	4350
20425	1069	455	96.9	0.82	1170	1880	1580	1.5	51.5	-	✓	✓	1FW4455-1HD ■ 0-1AA0	4680
24900	1303	503	97.0	0.83	1340	2200	2150	1.5	89.3	✓	✓	✓	1FW4503-1HD ■ 0-1AA0	5610
29565	1548	505	97.2	0.84	1570	4)	4)	1.5	102.6	✓	4)	4)	1FW4505-1HD ■ 0-1AA0	6110
34235	1792	507	97.3	0.84	1820	4)	4)	1.5	118.4	✓	4)	4)	1FW4507-1HD ■ 0-1AA0	6680
<b>600 rpm, IP55 degree of protection, IMB3 type of construction</b>														
8125	510	401	97.0	0.90	490	800	710	1.5	19.4	-	-	-	1FW4401-1HE ■ 0-1AA0	3040
9750	612	403	97.1	0.90	580	940	820	1.5	22.4	-	-	-	1FW4403-1HE ■ 0-1AA0	3310
11375	714	405	97.2	0.90	700	1090	940	1.5	26.1	-	-	-	1FW4405-1HE ■ 0-1AA0	3650
13000	816	407	97.3	0.93	750	1250	1070	1.5	30.9	-	✓	-	1FW4407-1HE ■ 0-1AA0	4100
14805	930	451	96.9	0.81	1050	1610	1580	1.5	37.9	-	✓	✓	1FW4451-1HE ■ 0-1AA0	4010
17325	1088	453	97.0	0.82	1160	1870	1850	1.5	44.9	-	✓	✓	1FW4453-1HE ■ 0-1AA0	4350
19950	1253	455	97.0	0.83	1300	2280	1850	1.5	51.5	✓	✓	✓	1FW4455-1HE ■ 0-1AA0	4680
24000	1507	503	97.4	0.87	1490	4)	2160	1.5	89.3	✓	4)	✓	1FW4503-1HE ■ 0-1AA0	5610
28500	1790	505	97.4	0.86	1780	4)	4)	1.5	102.6	✓	4)	4)	1FW4505-1HE ■ 0-1AA0	6110
33000	2073	507	97.5	0.84	2100	4)	4)	1.5	118.4	✓	4)	4)	1FW4507-1HE ■ 0-1AA0	6680
<b>800 rpm, IP55 degree of protection, IMB3 type of construction</b>														
7500	628	401	97.2	0.91	590	990	850	1.5	19.4	-	-	-	1FW4401-1HF ■ 0-1AA0	3040
9000	753	403	97.2	0.91	740	1190	1010	1.5	22.4	-	-	-	1FW4403-1HF ■ 0-1AA0	3310
10500	879	405	97.3	0.92	830	1460	1180	1.5	26.1	-	✓	-	1FW4405-1HF ■ 0-1AA0	3650
12000	1005	407	97.3	0.92	930	1500	1400	1.5	30.9	-	✓	✓	1FW4407-1HF ■ 0-1AA0	4100
14100	1181	451	96.9	0.82	1290	2260	1810	1.5	37.9	✓	✓	✓	1FW4451-1HF ■ 0-1AA0	4010
16500	1382	453	97.3	0.83	1470	2290	2210	1.5	44.9	✓	✓	✓	1FW4453-1HF ■ 0-1AA0	4350
19000	1591	455	97.4	0.90	1510	4)	2270	1.5	51.5	✓	4)	✓	1FW4455-1HF ■ 0-1AA0	4680
<b>Rated voltage</b>													4 7 8 9	-Z
• 460 V √														
• 690 V √														
• 400 V √														
Special voltage														
Other rated speed with additional plain text														

### Notes for current-calculation:

The stator current from permanent-excited motors can not be calculated as usual with the rated output, converter output voltage, power factor and efficiency. The reason is that the induced voltage at the rated point does not comply with the converter output voltage automatically. The real terminal voltage is depending on the speed, the torque and the integer number of turns.

The stator current of the 1FW4-motor series is proportional to the speed. With it the required stator current for a torque differing from the rated torque can be calculated. The stator current should be calculated exactly with the project tool „SINAMICS MICROMASTER SIZER“.

1) Temperature class 155 (temperature class F), used according to temperature class 155 (temperature class F)  
 2) Maximum torque  $T_{max}$  = Overload torque for 120 s (higher overload torques on request)

3) In the version with two galvanically isolated winding systems, two main terminal boxes 1XB1 631 are required.  
 - Not applicable  
 ✓ Applicable  
 4) Cannot be implemented

## Special versions

Special versions	Order code	Comments
<b>Motor protection</b>		
Motor temperature monitoring using built-in temperature sensor 1 x KTY 84-130	A23	
Motor temperature monitoring using built-in temperature sensor 2 x KTY 84-130	A25	
2 PT100 resistance thermometers or 3-wire for 4-wire circuit from terminals, without evaluation unit for rolling-contact bearings	A40	
2 PT100 dual resistance thermometers for 3-wire or 4-wire circuit from terminals, without evaluation unit for rolling-contact bearings	A42	
6 PT100 resistance thermometers for winding temperature monitoring for 3-wire or 4-wire circuit from terminals	A65	
Rolling-contact bearing monitor based on SPM shock pulse method, complete alarm box	H07	
<b>Motor connection and connection boxes</b>		
Two-part plate on connection box	K06	
Cable entry DIN 89280, maximum configuration	K57	
Rotation of the terminal box through 90°, entry from DE (This option is only possible when the motor can only be implemented with one terminal box).	K83	
Rotation of the terminal box through 90°, entry from NDE. (This option is only possible when the motor can only be implemented with one terminal box).	K84	
Rotation of connection box through 180°	K85	
Undrilled cable entry plate	L01	
Auxiliary terminal box with cast-iron housing	M50	
Auxiliary terminal box with stainless-steel housing	M51	
Separate auxiliary terminal box with cable entry for heater	M52	
Auxiliary terminal box with aluminium housing	M88	
<b>Shaft and rotor</b>		
Standard cylindrical shaft end, but without keyway	K42	
Non-standard cylindrical shaft end (only when technically possible); additional plain text stating the dimensions of the non-standard shaft end is required (in mm)	Y55	
<b>Coupling</b>		
Thrust ring for coupling guard	L15	
Mounting of supplied coupling	L17	
<b>Heating</b>		
Anti-condensation heating for 230 V supply voltage	K45	
Anti-condensation heating for 115 V supply voltage	K46	
Anti-condensation heating for 400 V supply voltage	L08	
Anti-condensation heating for 500 V supply voltage	L09	
Anti-condensation heating for other supply voltages (with plain text for voltage)	Y83	
<b>Colors and paint finish</b>		
Unpainted (primed)	K23	
Special paint finish in standard color	K26	
Normal paint finish not in standard color	Y53	
Special paint finish not in standard color	Y54	
<b>Special mounting technology</b>		
Mounting of absolute encoder EQN 425 EnDat 2.1 2048	H81	
Mounting of absolute encoder HMG111 HTL + SSI	H82	
Mounting of incremental encoder HOG10 DN 2048	H83	
Mounting of incremental encoder HOG11 DN 2048	H84	
Mounting of incremental encoder LL861 (2048 pulses)	H85	
Mounting of a rotary pulse encoder in special design (with plain text for encoder designation)	Y70	
<b>Balance and vibration severity</b>		
Vibration severity grade B	K02	
Full-key balancing	L68	

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Special versions	Order code	Comments
<b>Mechanical design and degrees of protection</b>		
Bearing design for increased cantilever forces	K20	
IP56 degree of protection (non-heavy-sea)	K52	
Bolts for fixing machine to steel foundation	L31	
T-head bolts, anchor sleeves and soleplates for mounting on a concrete foundation	L33	
External screws made of stainless steel	P45	
<b>Anormal stator winding</b>		
Anormal stator winding for speeds below 170 rpm	L1Y	
<b>Cooling water inlet temperature and ambient temperature</b>		
Cooling water inlet temperature up to 30 °C (ambient temperature up to 45 °C), torque reduction 3%	D15	
Cooling water inlet temperature up to 35 °C (ambient temperature up to 50 °C), torque reduction 5%	D16	
Cooling water inlet temperature up to 40 °C (ambient temperature up to 55 °C), torque reduction 8%	D17	
Cooling water inlet temperature up to 45 °C (ambient temperature up to 60 °C), torque reduction 11%	D18	
<b>Marine version - Acceptance/certification</b>		
Individual acceptance by classification authority with witness-testing and acceptance inspection certificate 3.1.C	E09	
Individual acceptance by classification authority	E10	
Marine design to GL, CT 45 °C, temperature class 155 used according to 155 (F according to F)	E11	
Marine design to LR, CT 45 °C, temperature class 155 used according to 155 (F according to F)	E21	
Marine design to BV, CT 45 °C, temperature class 155 used according to 155 (F according to F)	E31	
Marine design to DNV, CT 45 °C, temperature class 155 used according to 155 (F according to F)	E51	
Marine design to ABS, CT 45 °C, temperature class 155 used according to 155 (F according to F)	E61	
Marine design to CCS, CT 45 °C, temperature class 155 used according to 155 (F according to F)	E71	
Marine design, higher ambient temperature and/or temperature class 155 used according to 130 (F according to B), with plain text for ambient temperature, utilization and classification society	E80	
<b>Rating plate and additional plates</b>		
Second rating plate, separately packed	K31	
Rating plate with different data	Y80	
Additional plate with ordering data (customer information in plain text)	Y82	
<b>Packaging, safety notes, documentation and test certificates</b>		
Acceptance test certificate 3.1 according to EN 10204	B02	
Documentation on CD	B21	
Document - EU manufacturer's declaration	B30	
Document - Electrical data sheet	B31	
Document - Order dimension drawing	B32	
Document - Routine test certificate	B33	
Documentation in German	D00	(Documentation in English standard)
Documentation in Russian	D56	
Documentation in Italian	D72	
Documentation in French	D77	
Documentation in Spanish	D78	
Documentation in Portuguese	D79	
Documentation in Swedish	D83	
Standard test (routine test), witnessed	F01	
Visual acceptance and report handover, witnessed	F03	
Heating test at rated operating point at converter, unwitnessed	F04	
Heating test at rated operating point at converter, witnessed	F05	

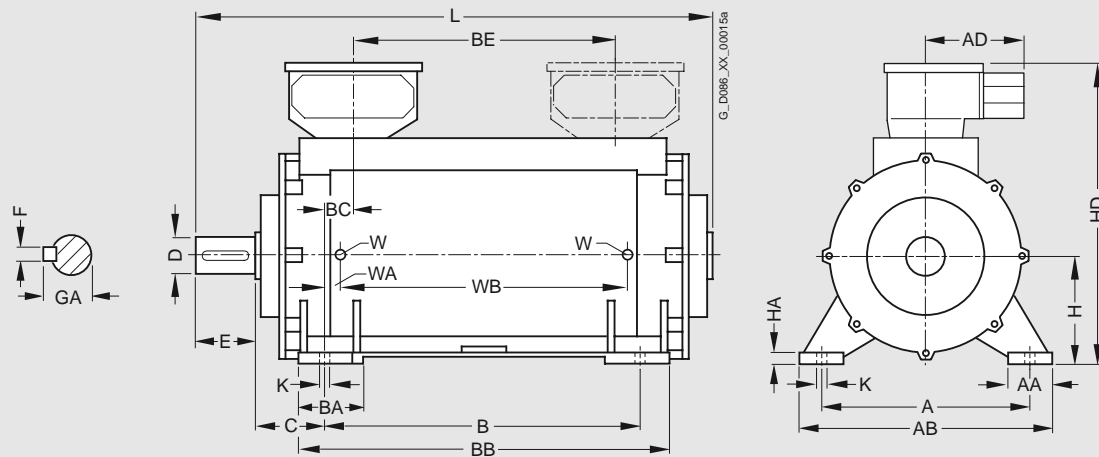
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Special versions	Order code	Comments
<b>Packaging, safety notes, documentation and test certificates (continued)</b>		
Recording of continuous short-circuit characteristic and calculation of losses, unwitnessed	<b>F16</b>	
Recording of continuous short-circuit characteristic and calculation of losses, witnessed	<b>F17</b>	
Recording of load characteristic (T-n-characteristic curve) on converter, unwitnessed	<b>F18</b>	
Recording of load characteristic (T-n-characteristic curve) on converter, witnessed	<b>F19</b>	
Noise measurement in no-load operation, no noise analysis, unwitnessed	<b>F28</b>	
Noise measurement in no-load operation, no noise analysis, witnessed	<b>F29</b>	
Noise measurement in no-load operation, with noise analysis, unwitnessed	<b>F62</b>	
Noise measurement in no-load operation, with noise analysis, witnessed	<b>F63</b>	
Type test with heat run for horizontal motors, unwitnessed	<b>F82</b>	
Type test with heat run for horizontal motors, witnessed	<b>F83</b>	
Customized acceptance on customer converter, additional information required	<b>F99</b>	

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### Dimension drawings



Type	Dimensions															
	A	AA	AB	AD <sup>1)</sup>	B	BA	BB	BC	BE	C	H	HA	HD	K	L	
1FW4401	750	150	900	400	1120	260	1365	155	880	254	400	30	1180	35	1880	
1FW4403																
1FW4405																
1FW4407																
1FW4451	850	180	1030	400	1250	265	1515	165	975	280	450	30	1280	42	2090	
1FW4453																
1FW4455																
1FW4503	950	180	1130	400	1400	300	1624	250	935	280	500	40	1385	42	2265	
1FW4505																
1FW4507	950	180	1130	400	1500	300	1782	135	628	315	500	40	1385	42	2415	
1FW4508																

Type	Dimensions for shaft extension according to DIN 748 "short"				Dimensions of cooling water connection <sup>2)</sup>		
	D	E	F	GA	W	WA	WB
1FW4401	150	200	36	158	G3/4"	50	780
1FW4403							
1FW4405							
1FW4407							
1FW4451	170	240	40	179	G1"	63	1175
1FW4453							
1FW4455							
1FW4503	190	280	45	200	G1 1/2"	85	1260
1FW4505							
1FW4507	190	280	45	200	G1 1/2"	40	1440
1FW4508							

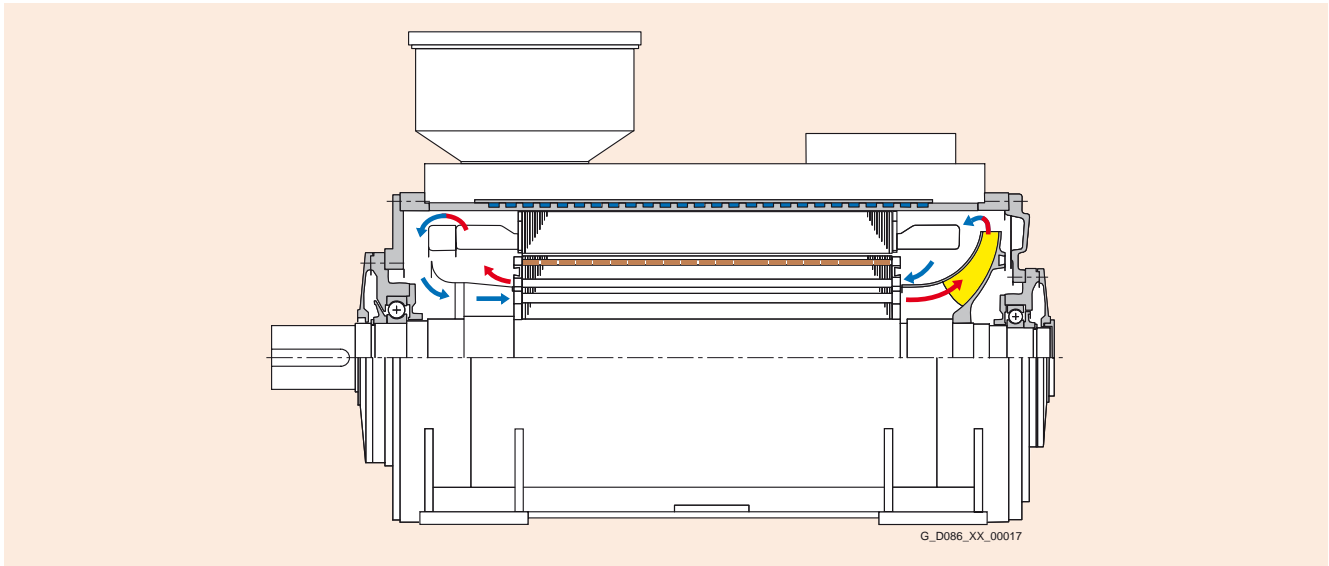
<sup>1)</sup> For 1XB1 631 terminal box.

<sup>2)</sup> The cooling water connection is available on both sides (RHS and LHS of motor).



## Further information

### Structure



Basic structure of the water-cooled HT-direct motor 1FW4

HT-direct motors have two cooling circuits that can be used to achieve intensive and effective cooling:

- The aluminium fan within the motor provides air circulation between DE and NDE. This cools, in particular, the stator winding overhang, the magnetic rotor and the bearings.
- The heat from the internal air is transferred to the cooling water through the motor housing.

### Frame design

A welded steel stator housing. The condensation water drainage holes are present and they are sealed during transport. For certain applications (e.g. in shipbuilding and the chemicals industry), external components made from aluminium are not permitted in the case of some customers. In these cases, aluminium components (e.g. terminal boxes) are replaced with other materials.

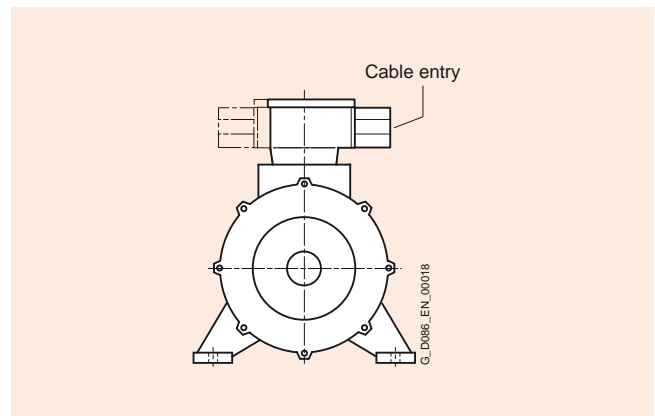
If external components are not permitted to be made from aluminium, this must be specified in plain text in the order.

### Position of the terminal box and cable entry

The terminal box is mounted **on the top**, in the **basic version at DE with cable entry from the right** (with view onto DE shaft extension). If a second terminal box is required, this is mounted behind it at NDE.

As an option, cable entry from the LHS is possible (order code **K85**).

When **only one** terminal box is mounted, cable entry is also possible from **DE** (order code **K83**) or **NDE** (order code **K84**).



Position of the terminal box and cable entry

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### Additional information

#### Packing weights and packing dimensions

Packing weights, tare

Type 1FW4 ...	Land transport on battens	Sea transport in wooden cases
	Type of construction IM B3	Type of construction IM B3
	kg	kg
... 401/403/405/407	70	280
... 451/453/455	75	340
... 503/505	80	390
... 507/508	85	410

Packing dimension = Largest motor dimension + Supplement

Dimensions	Supplements for	
	Land transport on battens	Sea transport in wooden cases
	Type of construction IM B3	Type of construction IM B3
	mm	mm
Length	+250	+250
Width	+200	+200
Height	+200	+500

#### Water-jacket cooling

To achieve a high power density, the motor housing is designed with water-jacket cooling.

The cooling water flows through a channel that runs in a spiral in the cooling jacket (from DE to NDE).

The cooling water inlet is at the drive end, on the LHS or RHS of the motor housing as required. The cooling water outlet is at the non-drive end, on the LHS or RHS of the motor housing as required (see dimension drawing). During transportation, the water inlet and outlet holes are sealed.

Cooling water flowrate and water pressure:

Type 1FW4 ...	Cooling water flow rate l/min	Maximum permissi- ble water pressure bar
... 401/403/405/407	30	5
... 451/453/455	50	5
... 503/505	65	5
... 507/508	80	5

The water quality must be taken into account:

- The cooling water should be chemically neutral, it should be clean, particles should have been filtered out and the following values must not be exceeded:
  - ph value 6.0 to 8.0
  - Overall hardness < 170 ppm
  - Chloride < 40 ppm
  - Sulfate < 50 ppm
  - Nitrate < 10 ppm
  - Iron < 0.2 ppm
  - Ammonium < 10 ppm
  - Loose material < 340 ppm
  - Conductance < 500  $\mu$ S/cm
- Max. size of any particles carried  $\leq$  0.1 mm
- No saltwater (sea water)
- If there is a danger of frost, then the appropriate anti-freeze measures are required for operation, storage and transport. For example, emptying and blowing-out with air, supplementary heating system for the cooling ducts.

- Additives must be mixed with the cooling water in appropriate quantities to protect against corrosion and the growth of algae. The type and quantity of additive should be taken from the manufacturer's specifications for these additives and the particular ambient conditions.

#### Materials used in the cooling circuit

Only steel is used in the cooling circuit. The heatsink material is not resistant to seawater. It is not permissible to directly cool the motors using seawater.

#### Different cooling water inlet temperature and site altitude

Cooling water inlet temperature  
(according to EN 60034-1 and IEC 60034-1)

The motors are designed for operation up to a cooling water inlet temperature of 25 °C, but still maintaining all of the specified motor data.

If the HT-direct motors are operated with higher cooling water inlet temperatures, the derating factors in the following table must be taken into account.

Derating factors for cooling water inlet temperatures >25 °C

Cooling water inlet temperature up to (ambient temperature up to)	25 °C	30 °C	35 °C	40 °C	45 °C
	(40 °C)	(45 °C)	(50 °C)	(55 °C)	(60 °C)
Derating factor $k_T$	1.0	0.97	0.95	0.92	0.89

This results in a maximum torque of the motor of:

$$T_{\max} = T_{\text{rated}} \cdot k_T$$

$T_{\max}$  = Maximum torque in Nm

$T_{\text{rated}}$  = Rated torque in Nm

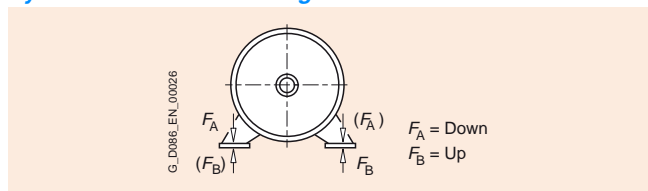
$k_T$  = Factor for different cooling water inlet temperature

If the maximum torque is no longer adequate for the drive, it should be checked whether the motor with the next higher rated torque fulfills the requirements.

Site altitude (according to EN 60034-1 and IEC 60034-1)

For site altitudes >1000 m above sea level, derating factors do not have to be taken into account for water-cooled HT-direct motors. They may, however, affect the dimensioning of the converter.

#### Dynamic foundation loading



Type	$F_A$ <sup>1)</sup> kN	$F_B$ <sup>1)</sup> kN
1FW4401-1 ...	53	22
1FW4403-1 ...	62	29
1FW4405-1 ...	72	35
1FW4407-1 ...	85	44
1FW4451-1 ...	91	51
1FW4453-1 ...	111	68
1FW4455-1 ...	136	90
1FW4503-1 ...	125	69
1FW4505-1 ...	148	88
1FW4507-1 ...	176	110
1FW4508-1 ...	205	132

<sup>1)</sup> Load at one motor long side (that is for two feet).