BALDOR · RELIANCE Series 15H Inverter



Design Specifications

- Process follower 0-5 VDC,
- 0-10 VDC, 4-20 mA
- Free run or ramp stop
- Selectable preset speeds
- Jog speed
- Dynamic braking (optional on size C2 and larger)
- DC injection braking
- · 2 analog meter outputs
- · 2 opto isolated outputs
- · 2 relay outputs
- Through wall & panel mount
- size C2, E and F.

Operator Keypad

3/4 thru 50 Hp

3/4 thru 450 Hp

3/4 thru 150 Hp

manufacturers (OEM).

- Forward/Reverse command
- Motor RUN and JOG
- · Local/Remote key
- Stop command
- · Parameter setting and display
- 32 character display
- Remote mount to 100 feet (60m) from control



when mounted on panel

• Service factor - 1.0 • Duty - continuous · Humidity - 90% max RH non-condensing

· Input frequency -

50 or 60Hz ±5%

• Input voltage

Environmental and

Operating Conditions

3 phase 200-240 VAC ±10%

3 phase 378-480 VAC ±10%

3 phase 573-600 VAC ±10%

• Altitude - 3300 feet (1000m) max without derate

230 VAC

460 VAC

575 VAC

Features: NEMA 1 enclosure as standard. Output frequency 0.25 to 400 Hz

with peak overload capacity of 170-200%. Separate accel/decel rates and controlled reversing. Built in two and three input PID process control loop.

Protective Features

Inverter/Vector Motors & Controls

- Selectable automatic restart at momentary power loss
- · DC bus charge indicator
- Fault indicator
- Adjustable time based overload • Cause of last 31 trips retained in memory
- Digital display for fault conditions
- Linear heat sink thermal sensor
- Isolated control circuitry

Output	Overload Capacity	150% for 60 seconds; 170-200% for 3 seconds for constant torque	
Ratings		115% for 60 seconds for variable torque	Ð
	Frequency	0.25-400 Hz	C Frame Motors
	Voltage	0-Maximum input voltage (RMS)	Mot F
Input Ratings	Frequency	50 or 60 Hz ± 5%	
	Voltage	180 - 264 VAC; 340 - 528 VAC, 515 - 660 VAC	
	Phase	Three phase (or single phase with derate)	
	Impedance	1% minimum for size C2, F, G and G2 (3% minimum required for size A, B, D and E)	ertz ers
Control Spec	Control Method	Sinewave carrier input, PWM output	50 Hertz Motors
	PWM Frequency	Adjustable 1-5 kHz standard, 1-15 kHz quiet	- 21
	V/Hz Ratio	Linear to squared reduced, base frequency, output voltage, minimum frequency limit, maximum frequency limit	
	Torque Boost	0-15% of input voltage; automatic with manual override	r s
	Brake Torque	20% standard on -E and -W; and -EO requires external assembly	Inverter/Vector otors & Controls
	Skip Frequency	Three zones 0-Max frequency	& C
	Frequency Setting	0-5 VDC, 0-10 VDC, 4-20mA, digital via optional RS232/485	Inverter/ Motors &
	Accel/Decel	Separate accel/decel rates, 0-3600 sec to maximum frequency	Ξų
Protective Functions	Inverter Trip	Over voltage, over current, under voltage, external trip, heatsink thermal, motor overload	
	Stall Prevention	Over voltage suppression, overcurrent suppression	sis ols
	External Output	OPTO isolated outputs, relay outputs, and LED indicator for trip	Motors Controls
	Short Circuit	Phase to phase, phase to ground	DC M and C
LCD Display	Running	Output frequency, set frequency, output current(%), voltage, RPM, custom units	5 -
	Setting	Parameter values for setup and review	
	Trip	Separate message for each trip, cause of last 31 trips retained in memory	s & Ikes
Ambient Conditions	Temperature	-10 to $+ 40^{\circ}$ C For UL Listing	Soft Starters & Dynamic Brakes
	Cooling	Forced air included when required	linic St

OPTIONS: See page 275-276 for optional Expansion Boards including RS-232, RS-485 isolated input etc. See page 273-274 for optional Dynamic Braking Assemblies.

Applications: Constant torque, variable torque or constant horsepower applications. New installations, replacements and original equipment

3 Phase - 50/60 Hz

3 Phase - 60 Hz

Farm Duty Motors 3 Phase - 50/60 Hz

Definite Purpose Motors

Unit Handling

Brake Motors

