Unit Handling

H2 Vector Drive



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(Linverter/Vector Motors & Controls

1 thru 3 Hp 115/230 VAC 1 Phase - 50/60 Hz 3/4 thru 75 Hp 230 VAC 3 Phase - 50/60 Hz 3/4 thru 150 Hp 460 VAC 3 Phase - 50/60 Hz 3/4 thru 150 Hp 575 VAC 3 Phase - 60 Hz

Applications: Constant torque or constant horsepower applications. New installations, replacements and original equipment manufacturers (OEM).

Features: NEMA 1 enclosure as standard. Output frequency 0 to 500 Hz with peak overload capacity of 175%. Automatic tuning to motor and full rated torque down to zero speed.

Input	Voltage	115	230	230	460	575
Ratings	Voltage (VAC)	95-130	180-264	180-264	340-528	515-660
naunys	Phase		Phase		nase (or single phase w	
	Frequency	50 or 60 Hz ±5%				
	Impedance	1% minimum from mains connection				
Output	Horsepower 1-3 HP @ 115/230VAC, 1PH; 1-75 HP @ 230VAC, 3PH; 1-125 HP @ 460VAC, 3PH; 1-125 HP @ 575VAC,					
•	'					
Ratings	Overload Capacity	Heavy Duty (Constant Torque) = 150% for 60 sec, 175% for 3 sec; Normal Duty (Variable Torque) = 115% for 60 sec				
	Frequency	0-500 Hz standard				
	Voltage	0-Maximum input voltage (RMS) (Note: 0 to 230 V for 115 V Single Phase Units)				
Protective	Trip	Missing control power, over current, over voltage, under voltage, over temperature (motor or control), output shorted or grounde				
Features	·	motor overload, encoder loss.				
	Stall Prevention	Over voltage suppression, overcurrent suppression				
	External Output	LED indicator for trip conditions, 4 assignable logic outputs, 2 assignable analog outputs				
	Short Circuit	Phase to phase, phase to ground				
	Electronic Motor Overload	Meets UL508C (I ² T)				
Environmental Conditions Keypad	Temperature	-10 to + 45°C, derate 3% per degree C above 45°C to maximum ambient temperature of 55°C				
	Cooling	Forced air				
	Enclosure	NEMA 1; NEMA 4X				
	Altitude	Sea level 3300 feet (1000m), derate 2% per 1000 ft (303m) above 3300 ft				
	Humidity	NEMA 1 – 90% maximum RH non-condensing; NEMA 4X – 100% condensing				
	Shock/ Vibration	1 G/ 0.5G at 10 Hz to 60 Hz				
	Storage Temperature	-10 to +65°C				
	Display	LCD graphical 128 x 64 pixel				
Display	Keys	14 key membrane with tactile feedback				
	Functions	Output status monitoring, Digital speed control, Parameter setting and display, Diagnostic and Fault log display, Motor run and				
	150 1 11 1	Local/Remote toggle, One-step tuning				
	LED Indicators	Forward run command, Reverse run command, Stop command, Jog active				
	Remote Mount	200 feet (60.6m) maximum from control, NEMA 4 Rated				
	Trip	Separate message and trace log for each trip, last 10 trips retained in memory				
Control	Control Method	Microprocessor controlled PWM output; selectable closed loop vector, encoderless vector or V/Hz inverter				
Spec	PWM Frequency	Adjustable 1-5 kHz standard,	5-16 kHz quiet			
	Frequency Setting	±5 VDC, 0-5 VDC ± 10 VDC, 0-10 VDC, 4-20 mA, 0-20 mA, digital (keypad), Serial Comms/USB 2.0 and ModBus RTU standar				
	Accel/Decel	0-3600 seconds				
	Brake Torque	20% standard on Sizes AA and B, 1% standard on Size C, D				
	Motor Matching	Automatic tuning to motor with manual override				
	-	MINT® WorkBench Software available via connection to USB 2.0 port for commissioning wizard,				
	PC Setup Software	firmware download, parameter viewer, scope capture, and cloning				
	Maximum Output Frequency	500 Hz				
	Maximum Output Frequency	500 HZ Keypad, Standard Run, 2-Wire, Standard Run 3-Wire, 15 Preset Speeds, Fan Pump 2-Wire, Fan Pump 3-Wire, Process Control				
	Selectable Operating Modes	lodes 3-SPD ANA 2-Wire, 3-SPD ANA 3-Wire, Electronic Pot 2-Wire, Electronic Pot 3-Wire, Network Profile Run, Bipolar Incremental encoder coupled to motor shaft; optional resolver feedback				
	. 0					
Motor	Feedback Type			er feedback		
Feedback	Pulses/Rev	60-20,000 selectable, 1024				
	Voltage Output	2 channel in quadrature, 5 VI	DC, differential			
	Marker Pulse	Required for position orientati	on			
	Power Input	5 VDC, 12 VDC, 300 mA max	imum			
	Max. Frequency	4 MHz				
	Positioning	Buffered encoder pulse train output for position loop controller				
Analog Inputs	One Differential	±5VDC, ±10VDC, 4-20 mA a				
	One Single Ended	0 - 10 VDC, 11-bit				
	Input Impedance	80 kOhms (Volt mode); 500 Ohms (Current mode)				
Analog Outputs			onins (Guitent mode)			
	Analog Outputs	2 Assignable AOUT1 (0-5V, 0-10V, 0-20mA or 4-20mA), AOUT2 (+5V, +10V)				
	Full Scale Range					
	Source Current	1 mA maximum (volt mode), 20mA (current mode)				
	Resolution	9 bits + sign				
Digital Inputs	Opto-isolated Inputs	8 Assignable, 1 dedicated inp				
	Rated Voltage	10 - 30 VDC (closed contacts std)				
Digital Outputs	Rated Voltage		5 to 30VDC or 240VAC (2 Re	lay Outputs)		
.ga. oatpato		60 mA Maximum (2 Opto Outputs); 5A Maximum non-inductive (2 Relay Outputs)				
	Maximum Current	OU IIIA MAXIIIIUIII (2 UDIO UII	lpuls); oa iviaximum non-madd	live (2 Relay Uulduls)		